

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S54	2	(position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) with (spring and pulley and tension and motor) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 18:15
S55	1	(position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) with (spring and pulley and tension and motor) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 18:23
S56	354	(position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) same (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 18:25
S57	610	(position location displac\$6) near6 ((measur\$6 sensor sensing detect\$4) same (control\$4 actuat\$4)) and (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) with (spring pulley tension motor) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 18:27
S58	354	(position location displac\$6) near3 (measur\$6 sensor sensing detect\$4) with (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 19:14

S59	38	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) and (control\$4 actuat\$4)) with (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 19:15
S60	13	(position location displac\$6) near3 ((measur\$6 sensor sensing detect\$4) and (control\$4 actuat\$4)) with (gravity gravitational) near3 (compensat\$4 force control \$4 actuat\$4) with (signal input output) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 19:27
S61	11	(gravity gravitation\$4) near3 compensat\$4 near3 (force control\$4 actuat\$4) with (output signal input) with position\$4 and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 19:47
S62	11	(gravity gravitation\$4) near6 compensat\$4 near6 (force control\$4 actuat\$4) with (output signal input) near6 position\$4 and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 20:23
S63	0	position\$4 near3 ((sens\$4 measur\$6 detect\$4) and (calculat\$4 comput\$6 control \$4) and actuat\$4) near3 (input output signal) and (gravity gravitation\$4) near3 compensat\$4 near3 ((calculat \$4 comput\$6 control\$4) and actuat\$4) near3 (input output signal) and (@ad< "20030807" @rlad< "20030807")	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 21:26

S64	3	position\$4 near6 ((sens\$4 measur\$6 detect\$4) and (calculat\$4 comput\$6 control\$4) and actuat\$4) near6 (input output signal) and (gravity gravitation\$4) near6 compensat\$4 near6 ((calculat\$4 comput\$6 control\$4) and actuat\$4) near6 (input output signal) and (@ad<"20030807" @rlad<"20030807"))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 21:28
S65	4	position\$4 near6 ((sens\$4 measur\$6 detect\$4) and (calculat\$4 comput\$6 control\$4) and actuat\$4) near6 (input output signal) and (gravity gravitation\$4) near6 (adjust\$4 compensat\$4 correct\$4) near6 ((calculat\$4 comput\$6 control\$4) and actuat\$4) near6 (input output signal) and (@ad<"20030807" @rlad<"20030807"))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 21:28
S66	2	position\$4 near6 ((sens\$4 measur\$6 detect\$4) and (calculat\$4 comput\$6 control\$4) and actuat\$4) near6 (input output signal) and (gravity gravitation\$4) near6 (adjust\$4 compensat\$4 correct\$4) near6 ((calculat\$4 comput\$6 control\$4) and actuat\$4) near6 (input output signal) near6 position\$4 and (@ad<"20030807" @rlad<"20030807"))	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/06/09 21:36

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